

CHAPTER-3 | Motion in a Plane

QUIZ
PART-03

1. In a 2-D frame, the components of a vector A of magnitude A making angle θ with the +x axis are:

- A. $A_x = A \sin \theta$, $A_y = A \cos \theta$
 - B. $A_x = A \cos \theta$, $A_y = A \sin \theta$
 - C. $A_x = A \tan \theta$, $A_y = A \cot \theta$
 - D. $A_x = A \sec \theta$, $A_y = A \csc \theta$
- (B)

Explanation : For 2-D resolution, $A_x = A \cos \theta$, $A_y = A \sin \theta$.

2. In 2-D, the magnitude A from rectangular components is:

- A. $H_A = \sqrt{(A_x A_y)}$
 - B. $A = A_x + A_y$
 - C. $A = \sqrt{(A_x^2 + A_y^2)}$
 - D. $A = |A_x - A_y|$
- (C)

Explanation : Squaring and adding the component relations gives $A^2 = A_x^2 + A_y^2$.

3. The direction θ of A in the xy-plane satisfies:

- A. $\tan \theta = A_x / A_y$
 - B. $\tan \theta = A_y / A_x$
 - C. $\tan \theta = A / A_x$
 - D. $\tan \theta = A / A_y$
- (D)

Explanation : From the right-triangle relation, $\tan \theta = A_y / A_x$.

4. In 3-D, the vector in unit-vector form is:

- A. $A = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$
 - B. $A = A \hat{i} + A \hat{j} + A \hat{k}$
 - C. $A = \hat{i} + \hat{j} + \hat{k}$
 - D. $A = A(\hat{i}\hat{j}\hat{k})$
- (A)

Explanation : The decomposition is $A = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$.

5. The 3-D magnitude-component relation is:

- A. $A^2 = A_x A_y A_z$
 - B. $A^2 = A_x^2 + A_y^2 + A_z^2$
 - C. $A^2 = (A_x + A_y + A_z)^2$
 - D. $A^2 = A_x^2 + A_y^2$
- (D)

Explanation : For 3-D resolution, $A^2 = A_x^2 + A_y^2 + A_z^2$.

6. If α, β, γ are the angles of A with the x, y, z axes, then:

- A. $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 0$
 - B. $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$
 - C. $\cos \alpha + \cos \beta + \cos \gamma = 1$
 - D. $\cos \alpha \cos \beta \cos \gamma = 1$
- (B)

Explanation : With $A_x = A \cos \alpha$, etc., one obtains $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$.

7. Displacement from (x_1, y_1) to (x_2, y_2) is:

- A. $\Delta r = (x_2 + y_2) \hat{i} + (x_1 + y_1) \hat{j}$
 - B. $\Delta r = (x_1 - x_2) \hat{i} + (y_1 - y_2) \hat{j}$
 - C. $\Delta r = (x_2 - x_1) \hat{i} + (y_2 - y_1) \hat{j}$
 - D. $\Delta r = (x_2 x_1) \hat{i} + (y_2 y_1) \hat{j}$
- (C)

Explanation : $\Delta r = r_2 - r_1 = (x_2 - x_1) \hat{i} + (y_2 - y_1) \hat{j}$.

8. The average velocity vector in a plane is defined as:

- A. $V_{avg} = \Delta r / \Delta t$
 - B. $V_{avg} = \Delta r \cdot \Delta t$
 - C. $V_{avg} = \Delta t / \Delta r$
 - D. $V_{avg} = \Delta r + \Delta t$
- (A)

Explanation : Average velocity is displacement per unit time.

9. The magnitude of average velocity from its components is:

- A. $V_{avg} = |V_x - V_y|$
 - B. $V_{avg} = \sqrt{(V_x^2 + V_y^2)}$
 - C. $V_{avg} = V_x + V_y$
 - D. $V_{avg} = \sqrt{(V_x V_y)}$
- (B)

Explanation : The relation is $V_{avg}^2 = V_x^2 + V_y^2 \Rightarrow V_{avg} = \sqrt{(V_x^2 + V_y^2)}$.

10. The average acceleration in a plane is given by:

- A. $a_{avg} = \Delta v / \Delta t$
 - B. $a_{avg} = \Delta v \cdot \Delta t$
 - C. $a_{avg} = \Delta t / \Delta v$
 - D. $a_{avg} = \Delta v + \Delta t$
- (A)

Explanation : Average acceleration is change in velocity per unit time.