

# **CLASS - 11**

# **PHYSICS**

Chapter - 3

**Motion in a Plane** 

Part - 1

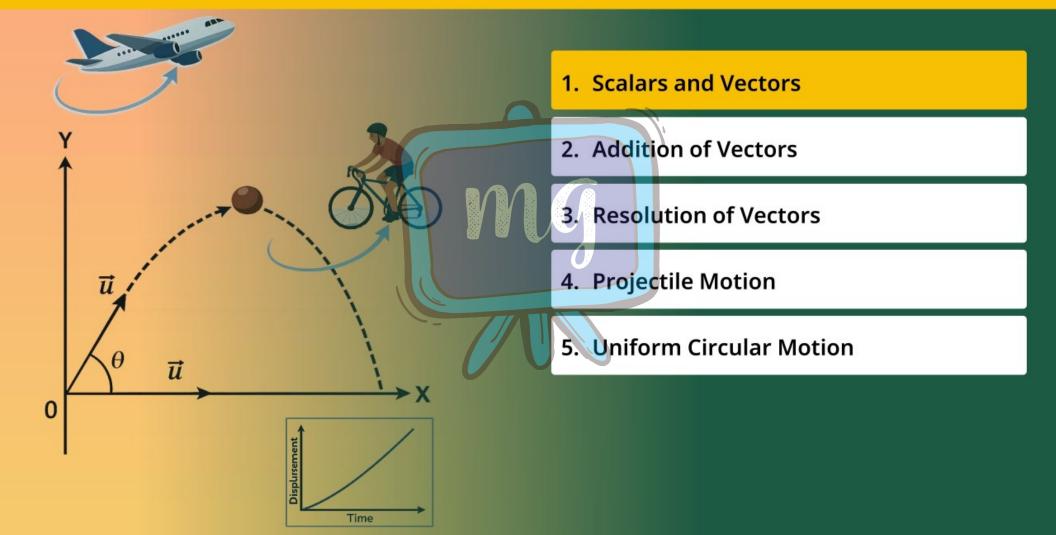
**Scalar and Vector Quantities** 

**Alok Gaur** 



# **OVERVIEW**









### **SCALAR QUANTITIES**

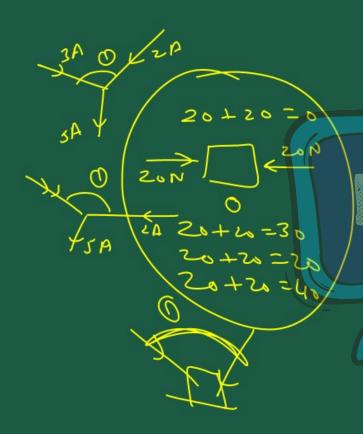
The physical quantities which have only magniture and no direction are called scalar quantities.

Example:

- Speed
- Work
- Electric flux etc.







### **VECTOR QUANTITIES**

The physical quantities which have both magniture and direction are called

vector quantities. follows vector laws

Example:

Acceleration

Force etc.

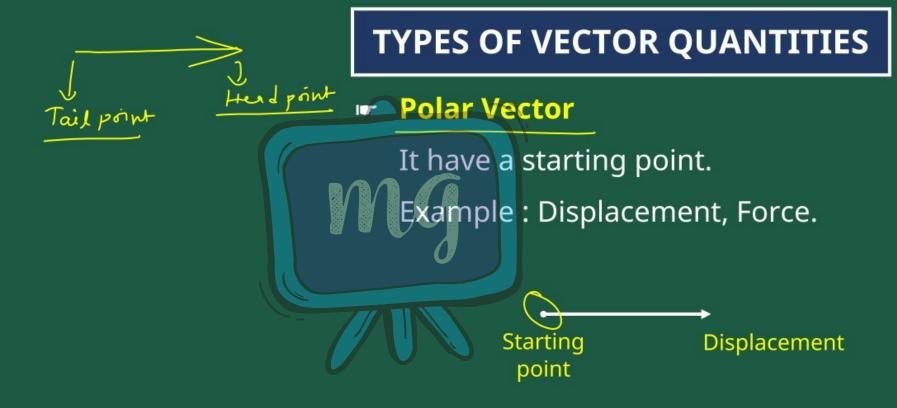
















### Axial Vector

It represents rotational effects. Example: Angular displacement, angular velocity. Axial Rotational vector



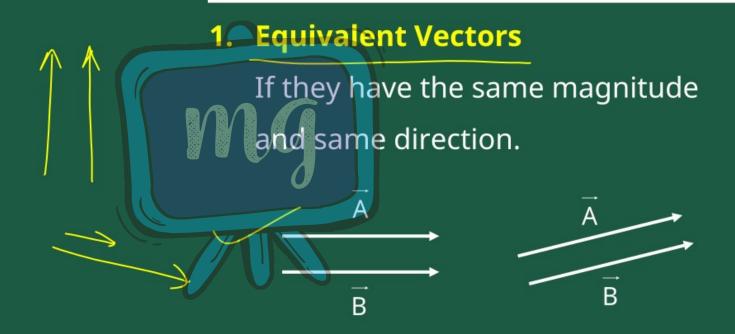
Tensor quantities: The physical quantities which have no specified direction and have different mass are called tensors.

Example: Moment of Intertia.





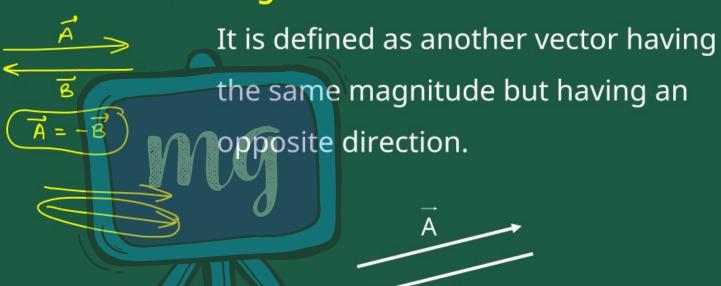
# **TYPES OF VECTOR**







### 2. Negative Vectors



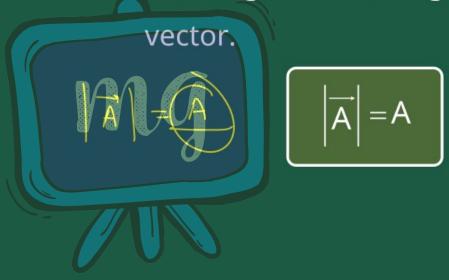




### 3. Modulus of a vector

A = A Â

The length or the magnitude of that









A unit vector is a vector of unit

magnitude drawn in the direction of

given vector.

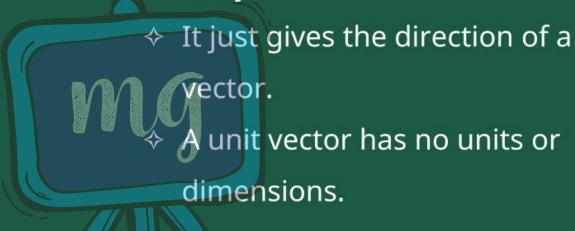


$$\widehat{A} = \frac{\overrightarrow{A}}{|\overrightarrow{A}|}$$





The magnitude of a unit vector is unity.



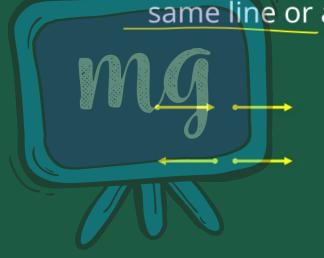




### 5. Collinear Vector

The vector which either act along the

same line or along parallel lines.



Like or parallel

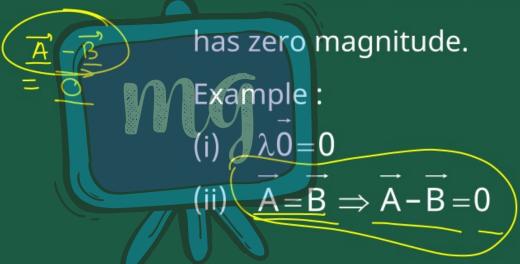
unlike or anti-parallel





6. Zero Vector

A zero or null vector is a vector that







### 7. Coplaner Vector

Coplaner vectors are the vectors which lie on the same plane in a three -dimensional space.



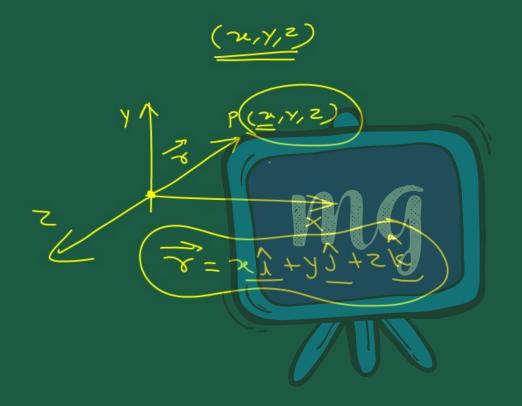


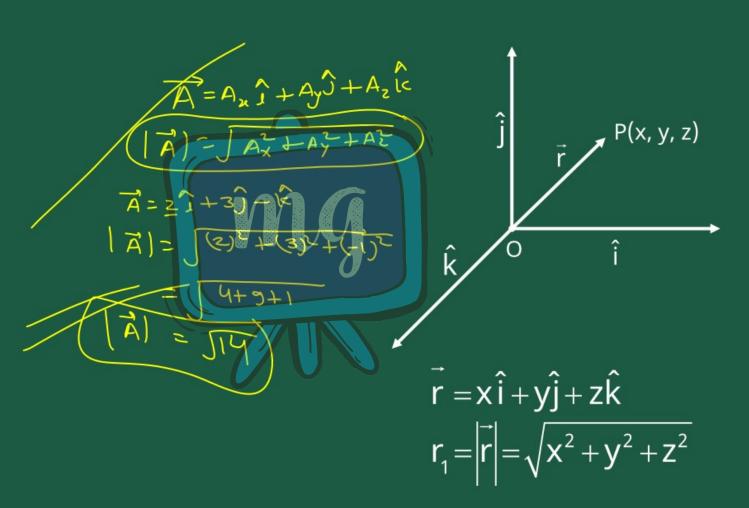
### **POSITION VECTOR**

The vector by which the position of a point is represented in the reference system is called the position vector.













### **DISPLACEMENT VECTOR**

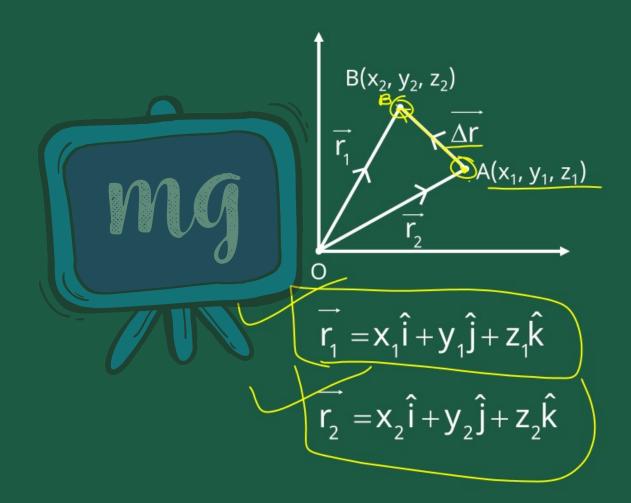
The distance covered by an object in a definite direction is called the displacement of the object.





The difference of two positions vectors that have the same origin point can be represented by placement vector. (The vectro joining the initial position of the particle with the final position)









$$\Delta r = r_{2} - r_{1}$$

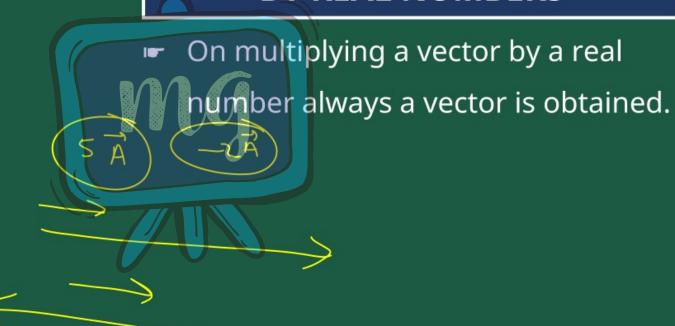
$$\Delta r = (x_{2} - x_{1})\hat{i} + (y_{2} - y_{1})\hat{j} + (z_{2} - z_{1})\hat{k}$$

$$\Delta r = \Delta r = \sqrt{(x_{2} - x_{1})^{2} + (y_{2} - y_{1})^{2} + (z_{2} - z_{1})^{2}}$$





# MULTIPLICATION OF VECTORS BY REAL NUMBERS





If the real number is positive then the magnitude of the vector obtained is equal to the product of magnitude of the vector and the number and the direction is along the direction of the given vector.

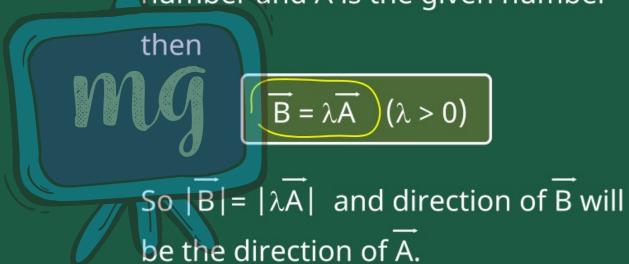




If the number is negative then the magnitude of the obtained vector is equal to the product of the magnitude of the vector and the number but the directin is opposite.



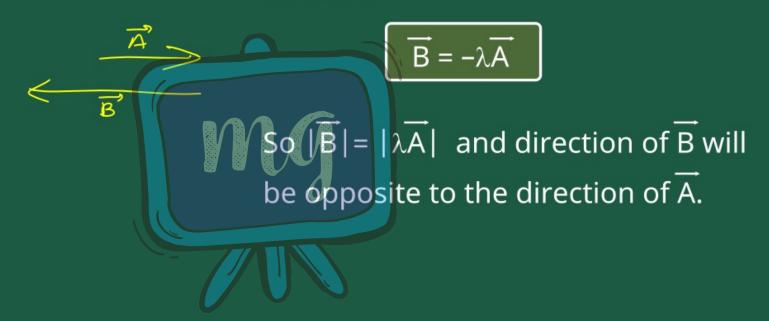
If  $\lambda$  is a rela number of positive number and  $\overrightarrow{A}$  is the given number







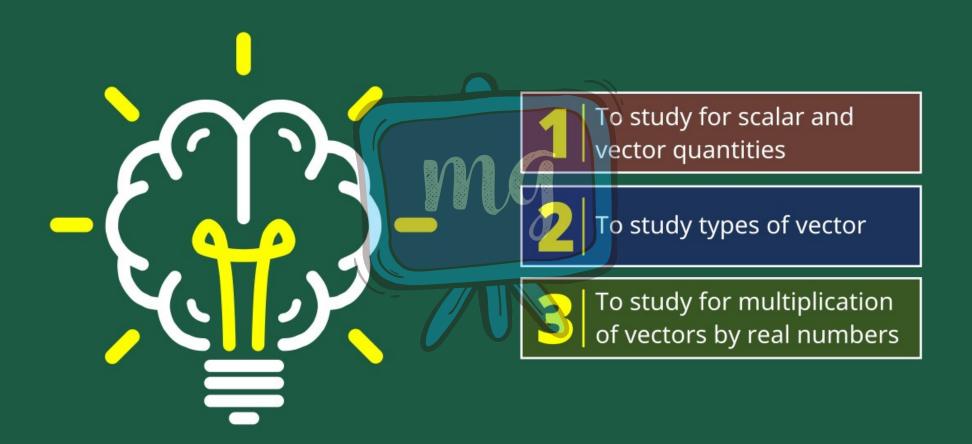
### Where if





## **LEARNING OUTCOMES**

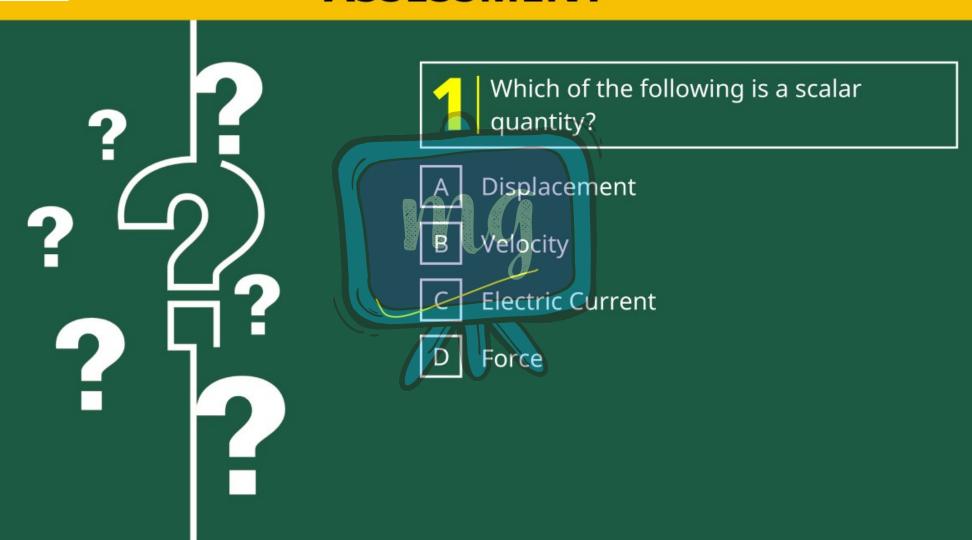






# **ASSESSMENT**

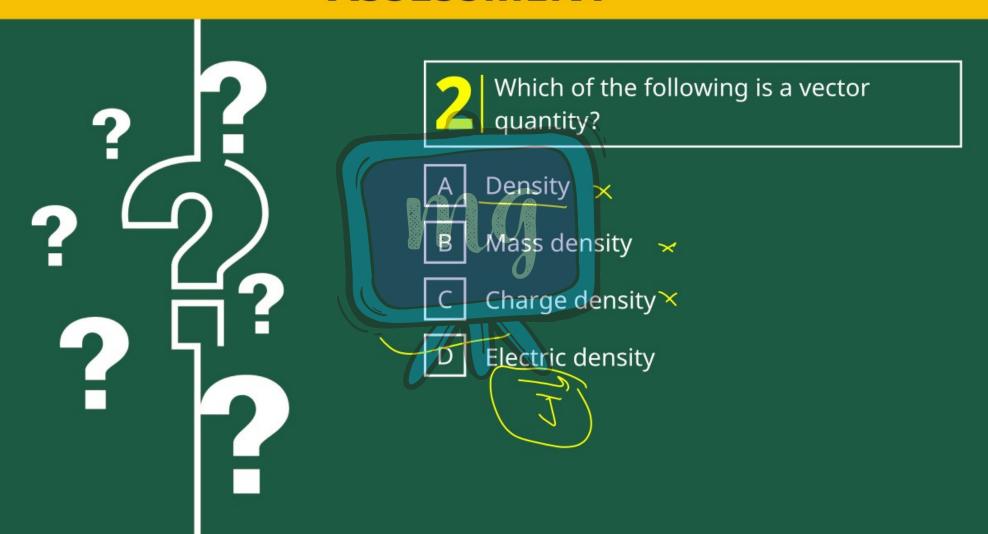






# **ASSESSMENT**







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